

Global Journal of Engineering and Technology Advances

eISSN: 2582-5003 Cross Ref DOI: 10.30574/gjeta Journal homepage: https://gjeta.com/



(RESEARCH ARTICLE)

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Remarks on fractional Hamiltonian formulation of discrete systems with examples

Noorhan Alshaikh and Jihad Hasan Asad *

Department of Physics, Faculty of applied Sciences, Palestine Technical University- Kadoorie, Tulkarm P 305, Palestine.

Global Journal of Engineering and Technology Advances, 2022, 11(01), 029-035

Publication history: Received on 02 March 2022; revised on 04 April 2022; accepted on 06 April 2022

Article DOI: https://doi.org/10.30574/gjeta.2022.11.1.0065

Abstract

The Fractional Hamiltonian is used to investigate discrete systems in terms of Caputo's fractional derivatives. Three models have been introduced and studied in order to apply the formalism presented here. The obtained Hamilton's equations of motion are exactly in agreement with the classical Hamiltonian formulation equations.

Keywords: Caputo's Fractional Derivatives; Lagrangian; Hamiltonian Formalution; Euler-Lagrange Equations; Discrete Systems

1. Introduction

Fractional calculus is a generalization of usual calculus. In this branch of mathematics, meanings are established for integrals and derivatives of any non-integer (even complex) order, such as $\frac{d^{1/2} f(t)}{dt^{1/2}}$. It has started in 1695 when Leibniz

presented his investigation of the derivative of order $\frac{1}{2}$. During the last decades it was used to study numerous fields

of engineering and science [1-7]. Numerical investigation of fractional differential equations appeared in many researches [8-14], and it played an essential role in solving these equations numerically for several systems.

Fractional calculus has been used to reformulate the Euler– Lagrange problems fractionally. Riewe investigated nonconservative Lagrangian and Hamiltonian mechanics and for those cases formulated a version of the Euler–Lagrange equations (ELE's) [11]. Other researches work on fractional Lagrangian and Hamiltonian approaches, see [16–21] and the references therein.

In this paper we developed the fractional Hamiltonian equations of motion (FHEOM) for discrete systems in terms of Caputo's fractional derivatives. The paper is prepared as follows:

In Sect. 2, we discussed briefly the Caputo's fractional Lagrangian mechanics. In Sect. 3, we present the Caputo's fractional Hamiltonian formalism for discrete systems. In Sect. 4, illustrative examples are discussed using the formalism presented. Finally, we close this paper with a conclusion in Sec. 5.

2. Basic Tools for Caputo's Fractional Lagrangian

The left Caputo's fractional derivative (i.e., LCFD), and the right Caputo's fractional derivative (i.e., RCFD) read respectively as [1, 2]:

* Corresponding author: Jihad Hasan Asad; Email: n.ibraheem@ptuk.edu.ps

Department of Physics, Faculty of applied Sciences, Palestine Technical University, Kadoorie- Tulkarm P 305, Palestine.

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$${}_{a}^{c}D_{t}^{\alpha}f(t) = \frac{1}{\Gamma(n-\alpha)}\int_{a}^{t}(t-\tau)^{n-\alpha-1}\left(\frac{d}{d\tau}\right)^{n}f(\tau)d\tau.$$
(1)

$${}_{t}^{c}D_{b}^{\alpha}f(t) = \frac{1}{\Gamma(n-\alpha)}\int_{t}^{b}(\tau-t)^{n-\alpha-1}(-\frac{d}{d\tau})^{n}f(\tau)d\tau.$$
(2)

Note that α is the order of the derivative such that $n-1 \le \alpha \prec n$, and it is not equal to zero.

When α goes to an integer then, these two equations turned to the following two classical derivatives:

$${}_{a}^{c}D_{t}^{\alpha}f(t) = \left(\frac{d}{dt}\right)^{\alpha}f(t).$$
(3)

$$\int_{t}^{c} D_{b}^{\alpha} f(t) = \left(-\frac{d}{dt}\right)^{\alpha} f(t).$$
(4)

Now, let us consider the action of integral

$$S = \int L(\eta, {}^{c}_{a}D^{\alpha}_{t}\eta, {}^{c}_{t}D^{\beta}_{b}\eta, t)dt.$$
⁽⁵⁾

The corresponding (ELE's) are then obtained as:

$$\frac{\partial L}{\partial \eta} + {}^{c}_{t} D^{\alpha}_{b} \frac{\partial L}{\partial {}^{c}_{a} D^{\alpha}_{t} \eta} + {}^{c}_{a} D^{\beta}_{t} \frac{\partial L}{\partial {}^{c}_{t} D^{\beta}_{b} \eta} = 0.$$
(6)

As
$$\alpha$$
, $\beta \to 1$, we have ${}^{c}_{a}D^{\alpha}_{t} = \frac{d}{dt}$, and ${}^{c}_{t}D^{\beta}_{b} = -\frac{d}{dt}$, then (6) reduces to the classical ELE's

3. Caputo's Fractional Hamiltonian of Discrete Systems

Consider the Lagrangian of discrete systems that depends on the Caputo's fractional derivatives of coordinates with the following form:

$$L = L(\eta, {}_{a}^{c}D_{t}^{\alpha}\eta, {}_{t}^{c}D_{b}^{\beta}\eta, t).$$
⁽⁷⁾

with $0 \prec \alpha, \beta \prec 1$.

Introducing the generalized momenta:

$$P_{\alpha} = \frac{\partial L}{\partial_{a}^{c} D_{t}^{\alpha} \eta};$$
$$P_{\beta} = \frac{\partial L}{\partial_{t}^{c} D_{b}^{\beta} \eta}.$$
(8)

$$H = P_{\alpha} \begin{pmatrix} {}^{c}_{a} D_{t}^{\alpha} \eta \end{pmatrix} + P_{\beta} \begin{pmatrix} {}^{c}_{t} D_{b}^{\beta} \eta \end{pmatrix} - L.$$
(9)

Taking the total differential of the above Hamiltonian:

$$dH = P_{\alpha}(d_{a}^{c}D_{t}^{\alpha}\eta) + dP_{\alpha}(_{a}^{c}D_{t}^{\alpha}\eta) + P_{\beta}(d_{t}^{c}D_{b}^{\beta}\eta) + dP_{\beta}(_{t}^{c}D_{b}^{\beta}\eta) - \frac{\partial L}{\partial \eta}d\eta - \frac{\partial L}{\partial_{a}^{c}D_{t}^{\alpha}\eta}d_{a}^{c}D_{t}^{\alpha}\eta - \frac{\partial L}{\partial_{a}^{c}D_{t}^{\beta}\eta}d_{a}^{c}D_{t}^{\alpha}\eta - \frac{\partial L}{\partial_{a}^{c}D_{b}^{\beta}\eta}d_{t}^{c}D_{b}^{\beta}\eta - \frac{\partial L}{\partial t}dt.$$
(10)

Substituting (8) into (10), we get:

$$dH = dP_{\alpha} \left({}^{c}_{a} D^{\alpha}_{t} \eta \right) + dP_{\beta} \left({}^{c}_{t} D^{\beta}_{b} \eta \right) - \frac{\partial L}{\partial \eta} d\eta - \frac{\partial L}{\partial t} dt.$$
⁽¹¹⁾

Making use of (6), then (11) becomes:

$$dH = dP_{\alpha} \left({}^{c}_{a} D^{\alpha}_{t} \eta \right) + dP_{\beta} \left({}^{c}_{t} D^{\beta}_{b} \eta \right) - \left[{}^{c}_{t} D^{\alpha}_{b} P_{\alpha} + {}^{c}_{a} D^{\beta}_{t} P_{\beta} \right] d\eta - \frac{\partial L}{\partial t} dt .$$

$$\tag{12}$$

This means that the Hamiltonian is a function of

$$H = (\eta, P_{\alpha}, P_{\beta}, t) . \tag{13}$$

The total differential of (13) is:

$$dH = \frac{\partial H}{\partial \eta} d\eta + \frac{\partial H}{\partial P_{\alpha}} dP_{\alpha} + \frac{\partial H}{\partial P_{\beta}} dP_{\beta} - \frac{\partial H}{\partial t} dt.$$
(14)

Comparing (14) with (11), one gets the following FHEOM:

$$\frac{\partial H}{\partial P_{\alpha}} = {}^{c}_{a} D^{\alpha}_{t} \eta ;$$
$$\frac{\partial H}{\partial P_{\beta}} = {}^{c}_{t} D^{\beta}_{b} \eta ;$$
$$\frac{\partial H}{\partial t} = -\frac{\partial L}{\partial t} ;$$

and finally,

$$\frac{\partial H}{\partial q_{\alpha}} = \binom{c}{t} D_{b}^{\alpha} P_{\alpha} + \binom{c}{a} D_{t}^{\beta} P_{\beta}.$$
(15)

4. Illustrative Examples

In this section, three examples (Mathematical and Physical) will be investigated using the formalism presented in Sec. 3 above.

4.1. Firstly, let us consider the following Mathematical example as a first discrete system

$$S = \int_{0}^{1} L dt$$

$$L = \frac{1}{2} ({}_{0}^{c} D_{t}^{\alpha} \eta)^{2} + \frac{1}{2} ({}_{t}^{c} D_{1}^{\beta} \eta)^{2} + ({}_{0}^{c} D_{t}^{\alpha} \eta) ({}_{t}^{c} D_{1}^{\beta} \eta)$$

where

The generalized momenta (8) read:

$$P_{\alpha} = {}_{0}^{c} D_{t}^{\alpha} \eta + {}_{t}^{c} D_{1}^{\beta} \eta ;$$
$$P_{\beta} = {}_{t}^{c} D_{1}^{\beta} \eta + {}_{0}^{c} D_{t}^{\alpha} \eta .$$

Then according (9) the Hamiltonian can be calculated as:

$$H = \frac{1}{2}P_{\alpha}^2 = \frac{1}{2}P_{\beta}^2$$

As a result the HEM (15) read:

$$P_{\alpha} = {}^{c}_{0}D^{\alpha}_{t}\eta \Longrightarrow [{}^{c}_{0}D^{\alpha}_{t}\eta + {}^{c}_{t}D^{\beta}_{1}\eta] = {}^{c}_{0}D^{\alpha}_{t}\eta;$$
$$P_{\beta} = {}^{c}_{t}D^{\beta}_{1}\eta \Longrightarrow [{}^{c}_{0}D^{\alpha}_{t}\eta + {}^{c}_{t}D^{\beta}_{1}\eta] = {}^{c}_{t}D^{\beta}_{1}\eta;$$
$$0 = [{}^{c}_{t}D^{\beta}_{1}\eta + {}^{c}_{0}D^{\alpha}_{t}\eta] [{}^{c}_{0}D^{\alpha}_{t}\eta + {}^{c}_{t}D^{\beta}_{1}\eta].$$

This result is in exact agreement with that obtained by Agrawal [17].

4.2. Secondly, we study the following physical model

$$S = \int_{0}^{1} Ldt$$

where $L = \frac{1}{2} ({}_{0}^{c} D_{t}^{\alpha} \eta)^{2}$.

This fractional model is the analog of free motion in one- dimensional space.

The generalized momenta (8) read:

$$P_{\alpha} = {}_{0}^{c} D_{t}^{\alpha} \eta;$$
$$P_{\beta} = 0.$$

Now, making use of (9) the Hamiltonian is calculated as:

$$H = \frac{1}{2} P_{\alpha}^2$$

The HEM (15) read:

$$P_{\alpha} = {}_{0}^{c} D_{t}^{\alpha} \eta;$$
$${}_{t}^{c} D_{1}^{\beta} \eta = 0;$$
$$0 = ({}_{t}^{c} D_{1}^{\alpha} \eta) ({}_{0}^{c} D_{t}^{\alpha} \eta)$$

As $\alpha \to 1$ the last equation reads the classical equation of motion for a free motion in a one dimensional space, i.e., $\frac{d^2\eta}{dt^2} = 0.$

4.3. Finally, we study the following physical model

$$S = \int_{0}^{1} Ldt$$

where
$$L = \frac{1}{2}m({}_{0}^{c}D_{t}^{\alpha}\eta)^{2} + \frac{1}{2}k\eta^{2}.$$

This is the fractional analog of the classical Harmonic Oscillator.

The generalized momenta (8) read:

$$P_{\alpha} = m_0^c D_t^{\alpha} \eta;$$
$$\sum_{t=0}^{c} D_t^{\beta} \eta = 0$$

As a result the Hamiltonian is:

$$H = \frac{P_{\alpha}^2}{2m} - \frac{1}{2}k\eta^2$$

The HEM read:

$$P_{\alpha} = m_0^c D_t^{\alpha} \eta;$$

$$0 = {}_t^c D_1^{\beta} \eta;$$

$$-k\eta = m({}_t^c D_1^{\alpha} \eta)({}_0^c D_t^{\alpha} \eta).$$

Again, as $\alpha \to 1$ the last equation reads the classical equation of motion for a Harmonic Oscillator, i.e. $m \frac{d^2 \eta}{dt^2} - k\eta = 0$

5. Conclusion

Using the Caputo's fractional derivatives, the fractional Hamiltonian of discrete systems has been constructed. The Hamilton's equations have been attained for discrete systems, where some examples are studied. We note that as $\alpha \rightarrow 1$ then the fractional Hamilton's equations reduced to the classical equations.

Finally, it is noted that the Hamiltonian formulation is in exact agreement with the Lagrangain formulation

Compliance with ethical standards

Acknowledgments

The authors would like to thank Department of Physics- Palestine Technical University- Kadoorie for facilitating the Implementation of this research

Disclosure of conflict of interest

The authors declare no conflict of interest.

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Author's Short Biography



NOOHAN ALSHAIKH received her B.Sc. and M.Sc in degree in physics from An- Najah National University, Palestine (with honor) in 2009 and 2013, respectively. She is now preparing her Ph.D. degree theoretical physics at An-Najah National University, Palestine. Currently, she is a lecturer in physics at Palestine Technical University- Kadoorie, Palestine.



JIHAD HASAN ASAD received the B.Sc. and M.Sc. degrees in physics from An-Najah National University, Palestine, in 1995 and 1998, respectively, and the Ph.D. degree in theoretical physics from The University of Jordan, Amman, Jordan, in 2004. He is currently working as a Full Professor of theoretical physics with Palestine Technical University, Palestine. He serves as a member of program committee for several national and international conferences and finally, he serves as a reviewer for many international journals.